

EC centrifugal module - RadiPac

backward-curved, single-intake
with support bracket



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Nominal data

Type	K3G280-AU11-C3	
Motor	M3G084-GF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	3100
Power consumption	W	1000
Current draw	A	1.6
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	61.4	51.5
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		71.9	62
05 Variable speed drive		Yes	

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

09 Power consumption P_{ed}	kW	1
09 Air flow q_v	m ³ /h	2405
09 Pressure increase p_{fs}	Pa	844
10 Speed (rpm) n	min ⁻¹	3120
11 Specific ratio*		1.01

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

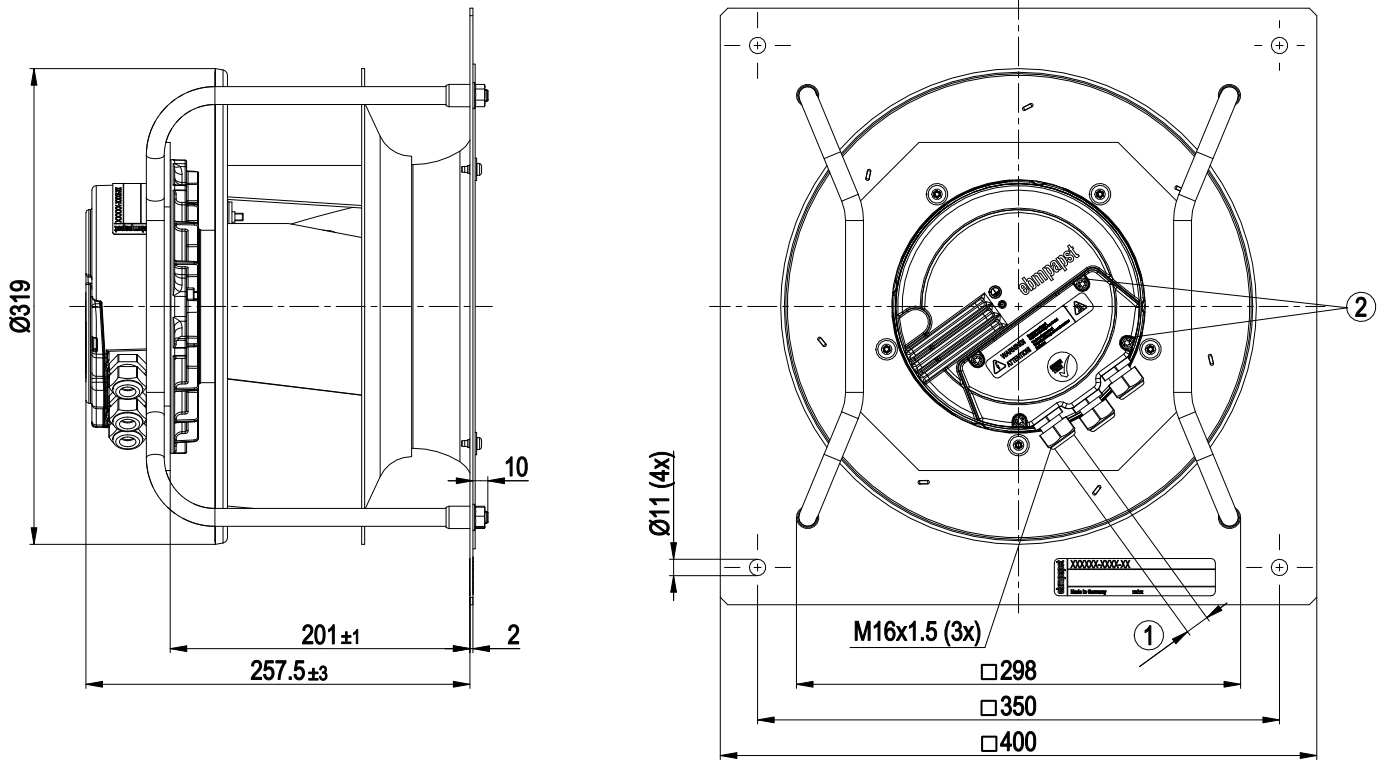
LU-147097



Technical description

Weight	11.52 kg
Size	280 mm
Motor size	84
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Support bracket material	Steel, painted black
Inlet nozzle material	Sheet steel, galvanized
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - Alarm relay - Power limiter - Motor current limitation - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (if protective earth is connected by customer to the housing's connection point)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC; UL 1004-7 + 60730-1; CCC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

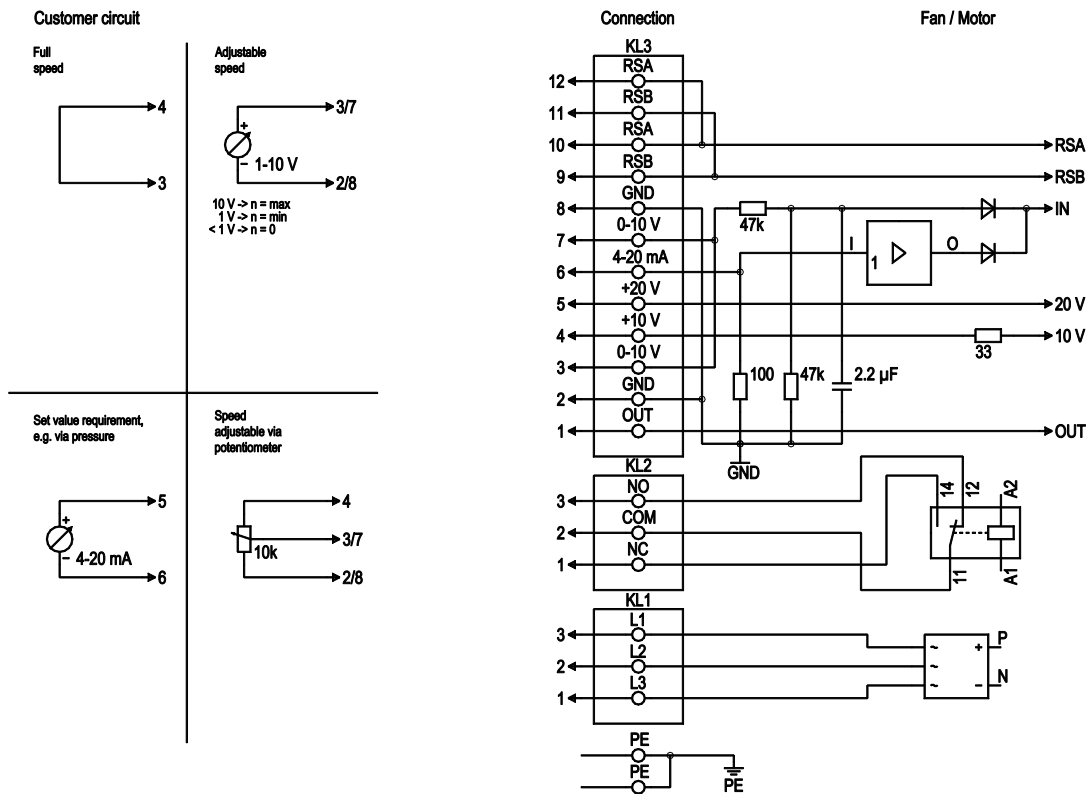
Product drawing



1 Cable diameter min. 4 mm, max. 10 mm, tightening torque 2.5 ± 0.4 Nm

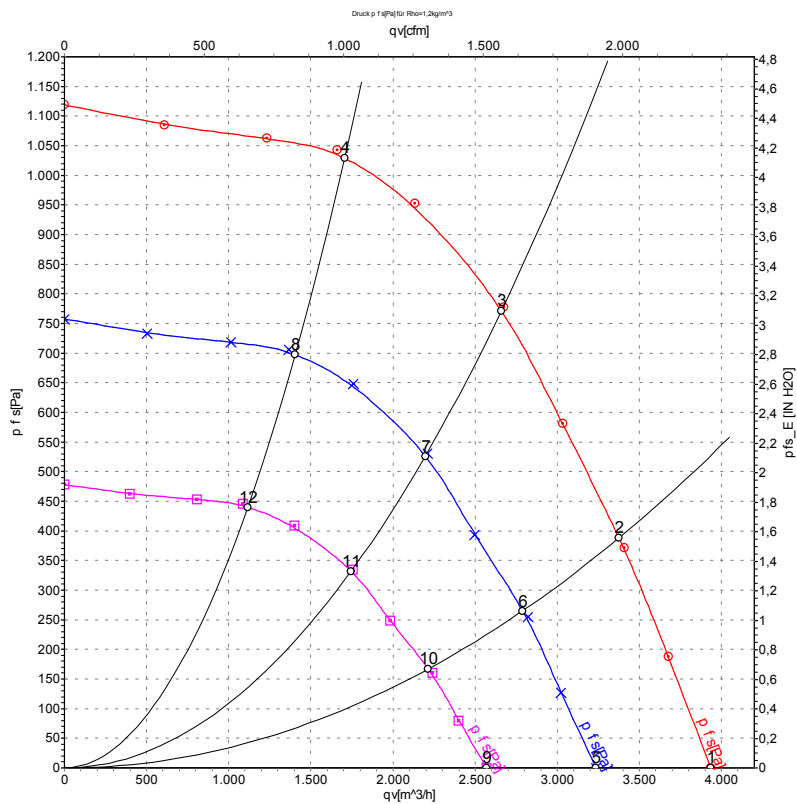
2 Tightening torque 3.5 ± 0.5 Nm

Connection diagram



No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply, voltage range (see nameplate), 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

Curves: Air performance 50 Hz



Measurement: LU-130335-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	p _{fs}	q _v	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa	cfm	in. wg
1	400	50	3100	645	1.04	78	86	93	3935	0	2315	0.00
2	400	50	3100	852	1.35	75	83	90	3375	390	1985	1.57
3	400	50	3100	1000	1.60	72	80	86	2660	775	1565	3.11
4	400	50	3100	921	1.46	76	83	89	1705	1030	1005	4.14
5	400	50	2575	358	0.58	74	82	88	3235	0	1905	0.00
6	400	50	2575	482	0.76	71	79	85	2790	269	1640	1.08
7	400	50	2575	562	0.89	68	76	82	2195	534	1295	2.14
8	400	50	2575	514	0.82	71	79	84	1405	700	825	2.81
9	400	50	2045	180	0.29	69	77	83	2570	0	1515	0.00
10	400	50	2045	242	0.38	66	74	80	2215	170	1305	0.68
11	400	50	2045	282	0.45	63	71	77	1745	337	1025	1.35
12	400	50	2045	257	0.41	66	74	79	1115	442	655	1.77

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
 LwA_{out} = Sound power level outlet side · q_v = Air flow · p_{fs} = Pressure increase