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Nominal data

Type	R3G280-AU11-C1	
Motor	M3G084-GF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	3100
Power consumption	W	1000
Current draw	A	1.6
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	64.6	51.2	09 Power consumption P_{ed}	kW	0.94
02 Measurement category		A		09 Air flow q_v	m ³ /h	2405
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	842
04 Efficiency grade N		75.4	62	10 Speed (rpm) n	min ⁻¹	3115
05 Variable speed drive		Yes		11 Specific ratio*		1.01

Data obtained at optimum efficiency level.

* Specific ratio = $1 + p_b / 100\,000\text{ Pa}$

LU-198028

The efficiency values displayed for achieving conformity with the Ecodesign Regulation EU 327/2011 has been reached with defined air duct components (e.g. inlet rings). The dimensions must be requested from ebm-papst. If other air conduction geometries are used on the installation side, the ebm-papst evaluation loses its validity/the conformity must be confirmed again. The product does not fall within the scope of Regulation (EU) 2019/1781 due to the exception specified in Article 2 (2a) (motors completely integrated into a product).



Technical description

Weight	6.6 kg
Size	280 mm
Motor size	84
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing; (sealed)
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Thermal overload protector (TOP) internally connected
Protection class assignment	I; If a protective earth is connected by the customer This component for installation may have several local protection classes. This information relates to this component's basic design. The final protection class is based on the component's intended installation and connection.
Conformity with standards	EN 61800-5-1; CE

R3G280-AU11-C1

EC centrifugal fan - RadiPac

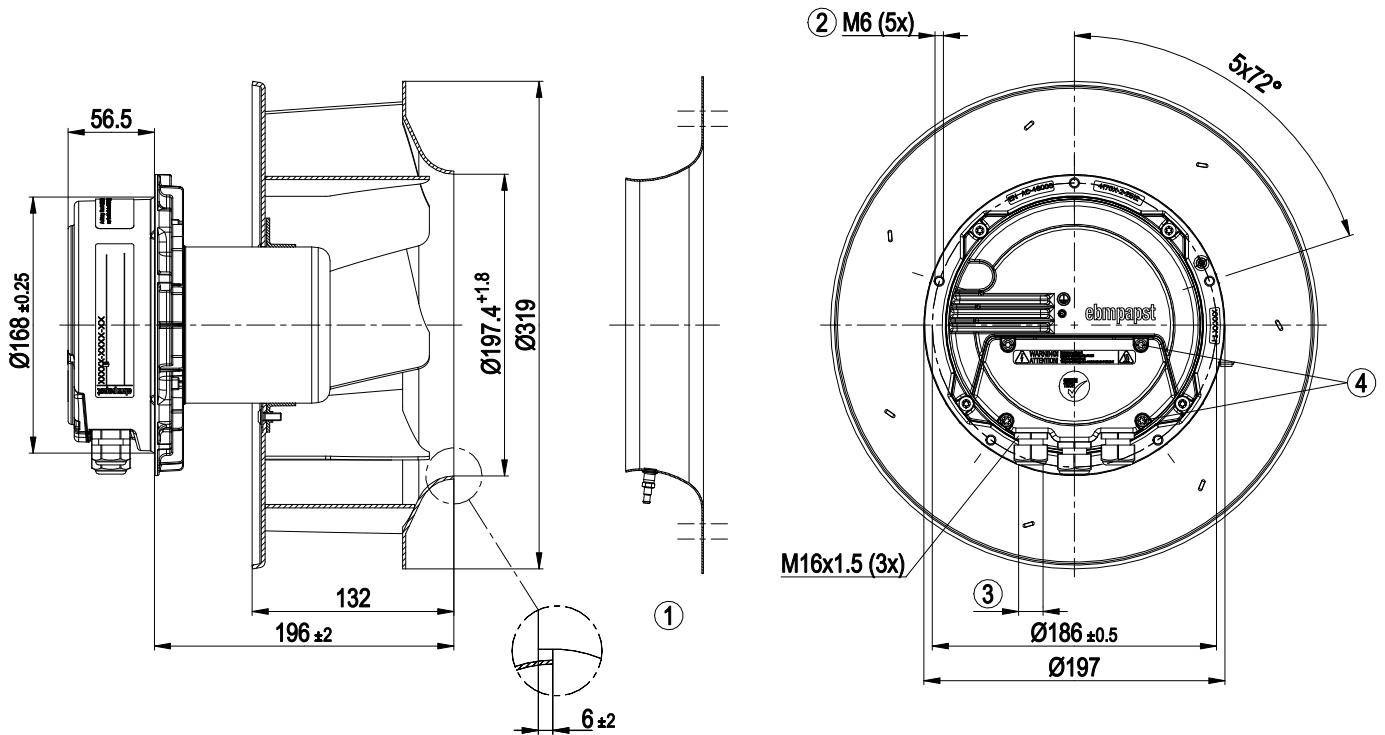
backward-curved, single-intake

Approval

CSA C22.2 No. 77 + CAN/CSA-E60730-1; CCC; EAC; UL 1004-7 + 60730-1

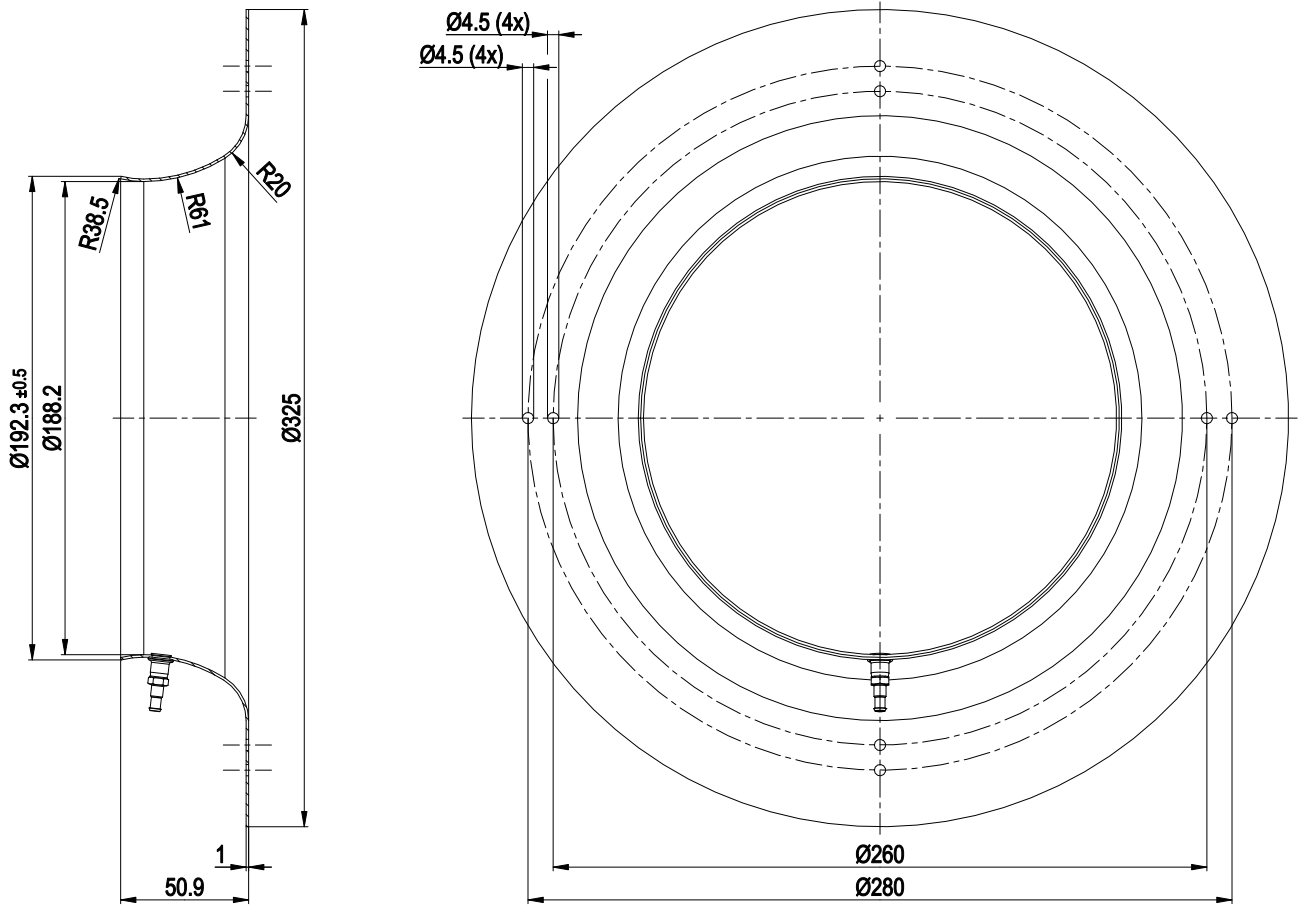


Product drawing



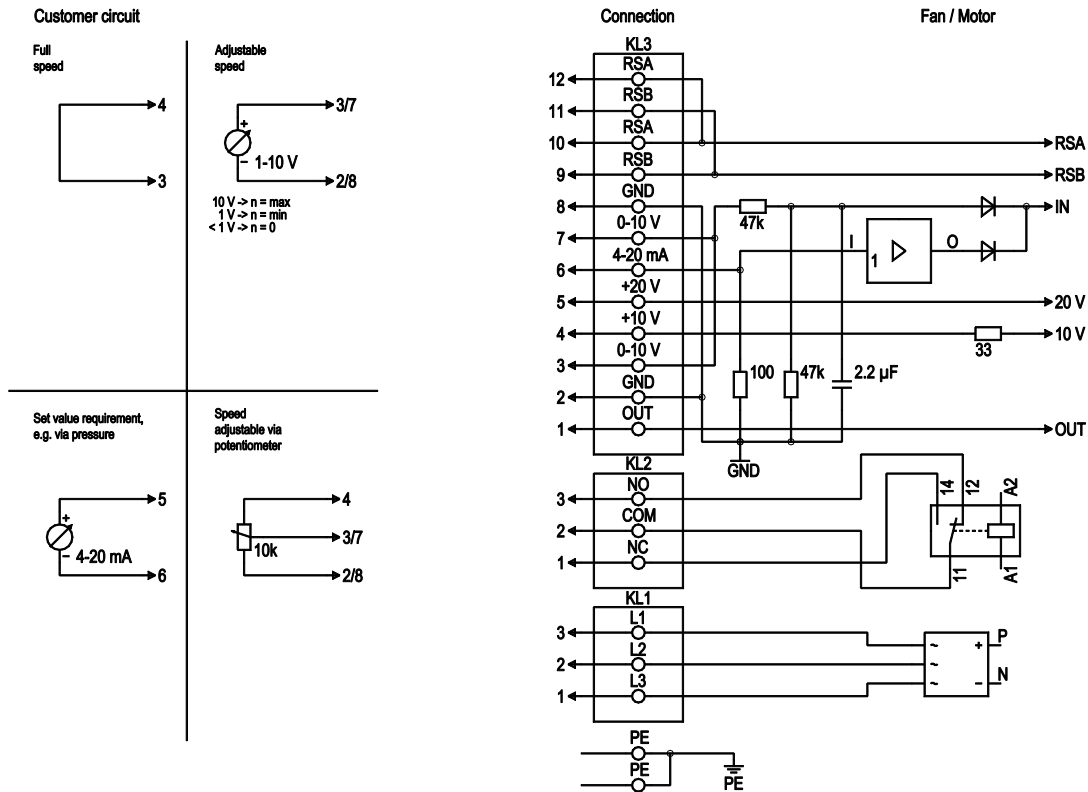
1	Accessory part: inlet ring 28075-2-4013 with pressure tap (k-factor: 93) not included in scope of delivery
2	Max. clearance for screw 16 mm
3	Cable diameter: min. 4 mm, max. 10 mm; tightening torque 2.5±0.4 Nm
4	Tightening torque 3.5 ± 0.5 Nm

Accessory part



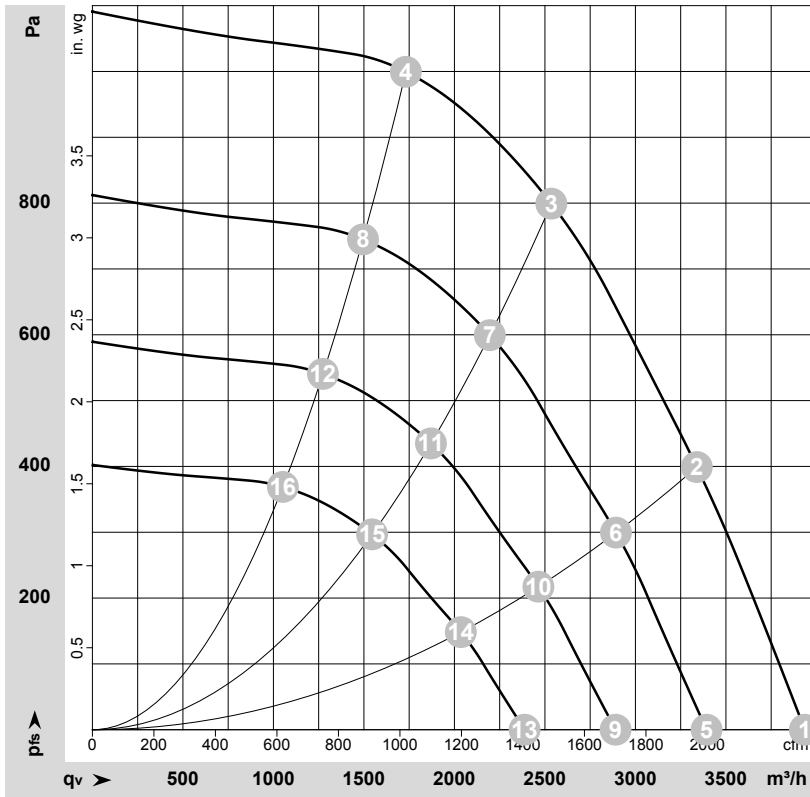
Inlet ring 28075-2-4013 with pressure tap (k-factor: 93)

Connection diagram



No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply, voltage range (see nameplate), 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

Curves: Air performance 50 Hz



$$\rho = 1.174 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-130335-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _V	p _{fs}	q _V	p _{fs}
		V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	3~	400	50	3100	645	1.04	78	86	93	3935	0	2315	0.00
2	3~	400	50	3100	855	1.36	75	83	89	3340	400	1965	1.61
3	3~	400	50	3100	1000	1.60	72	80	86	2535	800	1490	3.21
4	3~	400	50	3100	925	1.47	75	83	89	1730	1000	1020	4.01
5	3~	400	50	2700	413	0.67	74	82	89	3395	0	1995	0.00
6	3~	400	50	2700	557	0.88	71	79	86	2895	302	1705	1.21
7	3~	400	50	2700	647	1.03	68	76	83	2195	602	1295	2.42
8	3~	400	50	2700	595	0.94	72	79	85	1495	748	880	3.00
9	3~	400	50	2300	255	0.41	70	78	85	2890	0	1700	0.00
10	3~	400	50	2300	344	0.55	67	75	82	2465	219	1450	0.88
11	3~	400	50	2300	400	0.63	64	72	79	1870	436	1100	1.75
12	3~	400	50	2300	368	0.58	68	75	81	1275	542	750	2.18
13	3~	400	50	1900	144	0.23	66	73	80	2390	0	1405	0.00
14	3~	400	50	1900	194	0.31	62	70	77	2035	149	1200	0.60
15	3~	400	50	1900	225	0.36	59	67	74	1545	298	910	1.20
16	3~	400	50	1900	207	0.33	63	71	76	1050	370	620	1.49

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase